



The State of TACO in 2001

- Mission
- Humble Beginnings
- Features Chronology
- State of the Art
- Future



The TACO Mission

- Vision
 - a control system is a sea of networked objects ; every part of the control system should be a network object whether it is a low-level, high-level or application-oriented function
- Mission
 - to provide the best software for building networked objects and make it easy to use and freely available

TACO - Humble beginnings

- 1990 - a simple diagram, a simple api
- 1991 - first server controls a single bit
- 1992 - device servers control linac + booster
- 1993 - storage ring + first beamline

TACO - Features Chronology 1

1990	Research Chose ONC/RPC	Version 0
1991	Synchronous device servers Specific XDR data types	Version 1
1992	Source control under RCS Added generic XDR data types	Version 2
1993	Put commands + errors in database Defined Dserver Teams	Version 3
1994	Security Support for in-process clients	Version 4
1995	Servers in C++ Tcl/Tk clients Ported to Linux	Version 5



TACO - Features Chronology 2

1996	Added support for multiple nethost Added signal data types	Version 5
1997	ASynchronous device servers Ported to VxWorks Matlab clients	Version 6
1998	Java api Source code release + GPLed	
1999	Added events Python clients Labview clients + servers	Version 7
2000	Added support for TANGO Dynamic error handling	Version 8
2001	Workshop	



TACO - Device Model

- Commands
- State machine
- Client-server
- API
- Database
- Manager
- Security
- Signals

TACO - Platforms

- Linux on x86 + 68k
 - add ARM + PowerPC + 64bit
- Windows 95/98/NT/2000
 - updated November 2001 (V8.30)
 - update C++ port
- Solaris on SPARC
- OS9 on 68k
- HP-UX on HPPA
 - will die out ?
- Abandoned
 - VxWorks + LynxOS + Irix

TACO - Server Languages

- C++
 - workhorse
- C
 - ideal for embedded (footprint=25 kbytes)
- Python
 - cannot be simpler
- Labview
 - use as shared library

TACO - Client Languages

- C
 - workhorse
- Python
 - scripting language of the future
- Labview
 - quick (and dirty ?)
- Matlab
 - useful for scientific applications
- Tcl
 - will it die out ?

TACO - Communication

- synchronous
 - improve reimport algorithm
 - make TCP default protocol
- asynchronous
 - used quite a lot
- event-driven
 - not used at the ESRF !
 - re-subscribe to event if server restarted
- multiple control systems

TACO -Performance

Linux on a dual Pentium III 930 MHz	in same process	5 microseconds
Linux on a dual Pentium III 930 MHz	process to process on same computer	60 microseconds
Linux on a dual Pentium III 930 MHz	process to process on different computers	420 microseconds
Solaris on a SPARC	process to process on same computer	240 microseconds

TACO - Footprint

C server (shared)	25 kilobytes
C++ server (shared)	250 kilobytes



TACO - Threading

- single server thread for network
- server can setup polling thread
- client calls can be threaded
- objects can be in-process or out-of-process
- multiple worker threads supported
- when in doubt use mutexes

TACO - Database

- ndbm
 - replace with MySQL
- Oracle
- greta
- dbase tool (FRMII)



TACO - Data caching + Archiving

- Data collector
 - Make it simpler ?
- Archiving database (HDB)
 - Port to MySQL
 - should this be exported ?
 - Make it easier to configure



TACO - Applications

- Automatic class generator (is rarely used anymore)
- Fsigmon displays signals live
- Staticmon displays signals from archive database
- Xdevmenu for testing any device
- Specific applications for machine control
- SPEC for beamlines

TACO - Packaging

- Source code release via ftp
 - redo using autotools
- External access to source code tree
 - *taco.sourceforge.net* already registered
 - propose to move TACO source code there
- Documentation
 - 270+ pages of TACO manual
 - web site needs improvement

Worst of TACO

- Our worst errors were
 - Not implementing events earlier
 - Defining two api's (ds + dc)
 - Allowing specific types
- Worst platform was OS9
- Worst database was ndbm
- Worst algorithm was the reimport one (20 second wait)
- Main missing features are
 - clean startup procedure
 - good administration tool
 - alarms
 - SQL database
 - C++ api
 - Web support

TACO and TANGO

- TANGO is being developed using modern tools
- TANGO will improve TACO and avoid the same mistakes
- However TACO will continue to survive (ESRF has a huge TACO installation)
- TACO is complementary to TANGO (simpler and lighter BUT fewer features)
- PROPOSAL :
 - Make TACO and TANGO 100% compatible
 - TACO clients can call TANGO clients and vice versa in C++ and Java (switching will be done by API's)
 - TANGO servers can use TACO classes and vice versa in C++ (develop wrapper classes to do this)



TACO - The Future

- TANGO is the future @ ESRF
- full interoperability between TACO + TANGO
- minor improvements to TACO (adapt or die)
- provide public access to code tree
- GOALS
 - be as good if not better than the commercial solutions (e.g. OPC, commercial PLC's) while being easier to use
 - write device servers for ALL parts of the system
 - implement the killer idea, device server and/or client